

# Resilience Informatics for Innovation

— Classical Decision Theory —

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## Decision-making and rationality



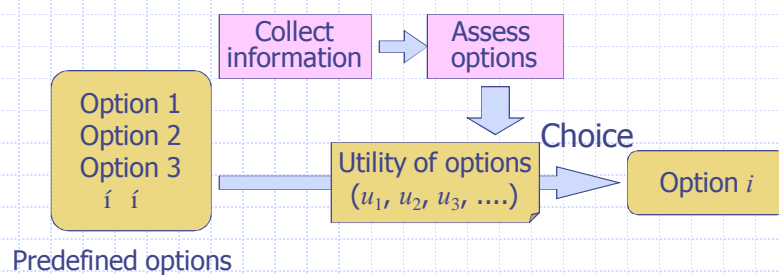
- ◆ What is decision-making?
  - Methodology for making a choice
  - The quality of decision-making determines success or failure of innovation and business.
- ◆ Rational decision-making
  - No means exist that certainly lead us to a correct decision due to uncertainties in the world.
  - Anyway, we need to decide rationally in some sense, **with no regret**. ⇒ Max. use of information



## Classical decision-making

### ◆ Normative model of decision-making

- Choosing one option from many
- Utility is what one wants to make maximum in the choice.



## Choice and preference

### ◆ Preference

- An act to choose one option from many
- Basic unit of classical decision

### ◆ Order of preference in a dyad

$a \succ b$   $a$  is preferred to  $b$ .

$a \approx b$   $a$  is equivalent to  $b$ .

$a \succeq b$   $a$  is preferred or equivalent to  $b$ .



## Utility and utility function

### ◆ Utility

- What one wants to make maximum in the choice
- Subjective value of each option evaluated by the decision-maker

### ◆ Utility function $u(x)$

- Mapping from the set of options to real numbers  
 $a \succeq b \Leftrightarrow u(a) \geq u(b)$
- Utility function is a tool to deal with the utility mathematically



## Condition for rational decision

◆ In order that the preference is mathematically consistent, it must be a weak order relation.

- Completeness

$$a \succeq b \text{ or } a \preceq b \text{ for any pair of } a \text{ and } b$$

- Transitivity

$$a \succeq b, b \succeq c \Rightarrow a \succeq c$$



## Expected utility

### ◆ Definition of expected utility

$$E = \sum_{i=1}^n u(s_i) p_i$$

$s_i$  : possible state

$p_i$  : occurrence probability of  $s_i$

$u(s_i)$  : utility of  $s_i$

### ◆ Expected utility hypothesis

- The utility of option  $a$  under uncertainty is represented by its expected utility  $E(a)$ .



## Example of expected utility

	Win.prob.	Prize	Consolation
Lottery 1	0.01	\$15,000	none
Lottery 2	0.02	\$8,000	none
Lottery 3	0.01	\$10,000	\$50

$$E(L1) = 0.01 \times \$15,000 = \$150$$

$$E(L2) = 0.02 \times \$8,000 = \$160$$

$$E(L3) = 0.01 \times \$10,000 + 0.99 \times \$50 = \$149.5$$



## Choice under uncertainty

### ◆ Uncertain situation

- $s_i$  : Possible state
- $p_i$  : Occurrence probability of  $s_i$
- $a_j$  : Option of action
- $u_{ij}$  : Utility when  $s_i$  obtains after  $a_j$  has been taken



## Various decision criteria (1)

### ◆ Expected utility criterion

$$a^* = a_j \quad \text{s.t.} \quad U(a_j) = \sum_{i=1}^n u_{ij} p_i \rightarrow \max$$

- If the occurrence probability distribution is unknown, suppose  $p_i = 1/n$  (Laplace criterion)

### ◆ Max-min criterion

$$a^* = a_j \quad \text{s.t.} \quad U(a_j) = \min_i u_{ij} \rightarrow \max$$

- Maximize the utility for the worst case



## Various decision criteria (2)

### ◆ Hurwitz criterion

$$a^* = a_j \text{ s.t. } U(a_j) = \alpha \max_i u_{ij} + (1 - \alpha) \min_i u_{ij} \rightarrow \max$$

- $\alpha = 0$  and  $\alpha = 1$  correspond to complete pessimism (max-min criterion) and complete optimism.

### ◆ Regret criterion (Minimum opportunity loss)

$$a^* = a_j \text{ s.t. } L(a_j) = \max_i r_{ij} \rightarrow \min$$

$$r_{ij} = \max_j u_{ij} - u_{ij}$$

- Opportunity loss  $r_{ij}$  is the degree of regret compared with the maximum utility obtainable with perfect foresight.



## Example of choice under uncertainty (1)

- ◆ You are a street food stall owner. Which sells well depends on the weather: ice cream or hot dog. Which will you stock more for tomorrow's business.

Weather	Sunny	Cloudy	Rainy
Probability	0.6	0.3	0.1
Ice cream	1,000	500	200
Half & half	800	700	450
Hot dog	650	600	500

## Example of choice under uncertainty (2)



Criterion	Expected	Laplace	Max-min
Ice cream	770	567	200
Half & half	735	650	450
Hot dog	620	583	500

Weather	Hurwitz*	Regret
Ice cream	600	300
Half & half	625	200
Hot dog	575	350

\*  $\alpha = 0.5$

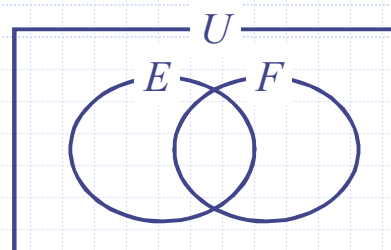
## Conditional probability



$U$  : Sample space

$E, F$  : Subset of  $U$

$|X|$  : Size of  $X$



Conditional probability

$$P(E|F) = \frac{|E \cap F|}{|F|} = \frac{|E \cap F| |U|}{|F| |U|} = \frac{P(E \cap F)}{P(F)}$$

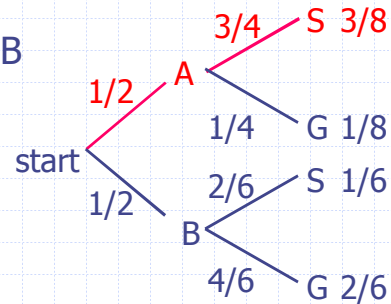
$$P(E \cap F) = P(E)P(F|E) = P(F)P(E|F)$$

## Example of conditional probability

- ◆ Two invisible bins A and B

A : 3 silver & 1 gold coins

B : 2 silver & 4 gold coins



- You drew a silver coin from either of the two bins by chance. Which bin did you choose?

$$P(A|S) = \frac{P(A \cap S)}{P(S)} = \frac{3/8}{3/8 + 1/6} = \frac{9}{13} \approx 0.692$$

## Independent events

- ◆ When event  $E$  and  $F$  satisfy the following conditions, they are independent.

$$P(E|F) = P(E) \quad P(F|E) = P(F)$$

- ◆ The following is the necessary and sufficient condition for that  $E$  and  $F$  are independent.

$$P(E \cap F) = P(E)P(F)$$





## Bayes theorem

$$P(F | E) = \frac{P(E | F)P(F)}{P(E)}$$

### ◆ General form of Bayes theorem

- $H_1, H_2, \dots, H_n$  are exclusive each other and

$$H_1 \cup H_2 \cup \dots \cup H_n = U$$

$$P(H_i | E) = \frac{P(H_i)P(E | H_i)}{P(H_1)P(E | H_1) + \dots + P(H_n)P(E | H_n)}$$

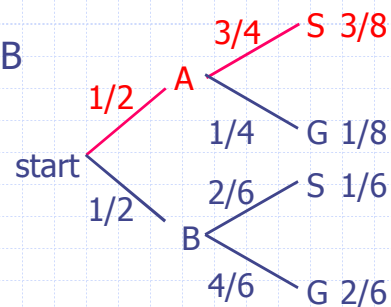


## Coins-in-bins problem revisited

### ◆ Two invisible bins A and B

A : 3 silver & 1 gold coins

B : 2 silver & 4 gold coins



- You drew a silver coin from either of the two bins by chance. Which bin did you choose?

$$P(A|S) = \frac{P(S|A)P(A)}{P(S|A)P(A) + P(S|B)P(B)} = \frac{3/4 \cdot 1/2}{3/4 \cdot 1/2 + 1/3 \cdot 1/2} = \frac{9}{13}$$



## Bayesian inference (1)

$H$  : Hypothesis

$E$  : Evidence, testimony, or symptom

$P(H)$  : Prior probability with no evidence

$P(H|E)$  : Posterior probability after  
evidence  $E$  has been obtained



## Bayesian inference (2)

◆ After  $E$  has been obtained, how we should modify the probability of  $H$ ?

$$P(H|E) = \frac{P(E|H)P(H)}{P(E)} \quad P(\bar{H}|E) = \frac{P(E|\bar{H})P(\bar{H})}{P(E)}$$

◆ Modification of odds in terms of  $E$

$$\frac{O(H|E)}{\text{Posterior odds}} = \frac{P(H|E)}{P(\bar{H}|E)} = \frac{P(E|H)P(H)}{P(E|\bar{H})P(\bar{H})} = \lambda_E \frac{O(H)}{\text{Prior odds}}$$



## Bayesian inference (3)

- ◆ After another evidence  $F$  has been obtained,

$$\begin{aligned}
 O(H|E \cap F) &= \frac{P(H|E \cap F)}{P(\bar{H}|E \cap F)} \\
 &= \frac{P(E|H) P(F|H) P(H)}{P(E|\bar{H}) P(F|\bar{H}) P(\bar{H})} = \underbrace{\lambda_E \lambda_F}_{\text{Modification factor for each evidence}} O(H)
 \end{aligned}$$



## Hasty doctor example

- ◆ You received a cancer test. The doctor said that 1 out of 1,000 is the average rate of cancer at your age. The test is accurate and it gives a correct result for 99% of cancer patients and 97% of non cancer patients. Your test result was positive, and the doctor recommended you hospitalization ASAP.

$$O(C|+) = \frac{P(+|C) P(C)}{P(+|\bar{C}) P(\bar{C})} = \frac{0.99 \times 0.001}{0.03 \times 0.999} \approx \frac{1}{30}$$

## Three prisoners problem (Monty Hall problem)



- ◆ Out of three prisoners, two will be executed and one will be freed tomorrow. Prisoner A heard from the jailor that B will be executed. A was delighted that his alive probability has increased from  $1/3$  to  $1/2$  with this information, since either A or C will be freed.

$$P(A|b) = \frac{P(A)P(b|A)}{P(A)P(b|A) + P(B)P(b|B) + P(C)P(b|C)}$$

$$= \frac{1/3 \cdot 1/2}{1/3 \cdot 1/2 + 1/3 \cdot 0 + 1/3 \cdot 1} = \frac{1}{3}$$

## Component failure example



- Failure statistics of a particular component are collected for every 100 days of operation, and the following data were obtained. Evaluate the failure rate.

Interval	1	2	3	4
Times of failures	6	3	5	6

$$\text{Average} = (6+3+5+6)/4/100 = 0.05 \text{ day}^{-1}$$

$$\text{STD} = 0.02 \text{ day}^{-1}$$



## Probability density function

- ◆ Cumulative distribution function  $F(x)$ 
  - Probability that a random variable  $X$  takes a value not greater than  $x$

$$F(x) = P(-\infty < X \leq x)$$

- ◆ Probability density function  $f(x)$

$$f(x) = \frac{dF(x)}{dx} \quad F(x) = \int_{-\infty}^x f(x) dx$$

$$f(x) dx \approx P(x < X \leq x + dx)$$



## Bayesian inference on distribution

$f(\theta)$  : Prior density function of  $\theta$

$f(\theta | A)$  : Posterior density function of  $\theta$

- ◆ Bayesian update of the density function after event  $A$  has been observed

$$f(\theta | A) = \frac{P(A | \theta) f(\theta)}{\int P(A | \theta) f(\theta) d\theta}$$

## Application of Bayesian approach to component failure example



### ◆ Poisson distribution

$$P(k | \lambda) = \frac{(\lambda T)^k}{k!} e^{-\lambda T}$$

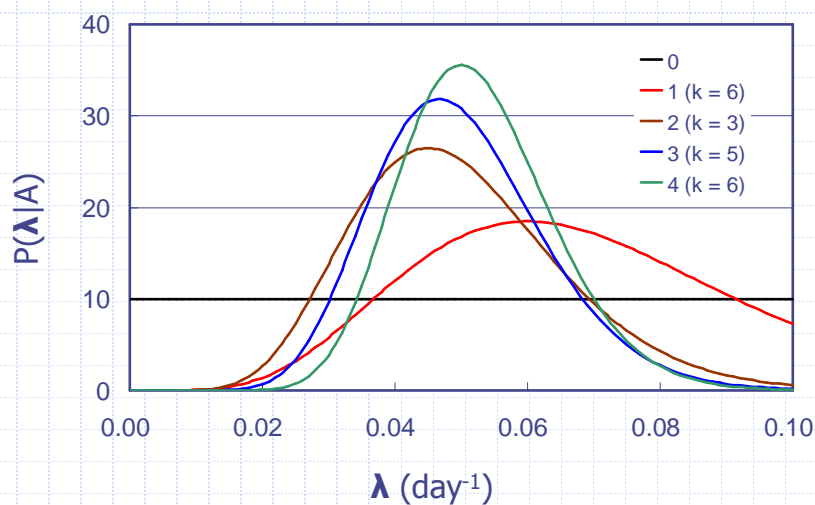
$\lambda$  : Failure rate

$T$  : Interval of observation (100 days)

$k$  : Times of failures observed

- Uniform distribution in  $[0, 0.1]$  is assumed for  $f(\lambda)$  at the beginning.

## Bayesian update of failure rate





## Concepts of probability (1)

### ◆ Normative definition (Pascal)

- Fraction of number of cases among the sample space

$$p = |A| / |U|$$

### ◆ Statistical definition (d'Alembert)

- Asymptotic value of event frequency

$$p = \lim_{n \rightarrow \infty} (f_n / n)$$



## Concepts of probability (2)

### ◆ Subjective definition (Bayes)

- Degree of individual confidence on occurrence of the event

### ◆ Informatics definition (Shannon)

- Amount of information that implies occurrence of the event

$$S = -\log_2 p$$